

Installation Instructions

Original Instructions



Allen-Bradley

by ROCKWELL AUTOMATION

ArmorKinetix 2090 Cables and Connectors

Catalog Numbers 2090-CDHIFS-12AF, 2090-CDHP1S-12AF, 2090-CSBM1P7-14AF, 2090-CPWFLP7-14AF, 2090-CFBM7S7-CDAF, 2090-CFBFLS7-CDAF, 2090-CDET, 2090-CDHT, 2090-CDFT, 2090-CDPT

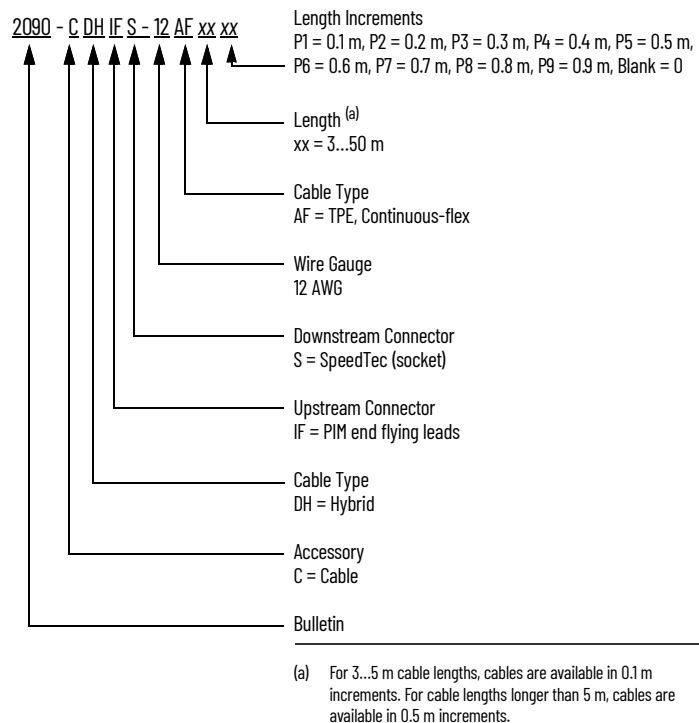
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Cable Catalog Numbers

Catalog numbers consist of various characters, each of which identifies a specific option for that component. Use the catalog numbering charts below to understand the configuration of your component. For the cable type: PUR = Polyurethane and TPE = Thermoplastic Elastomer.

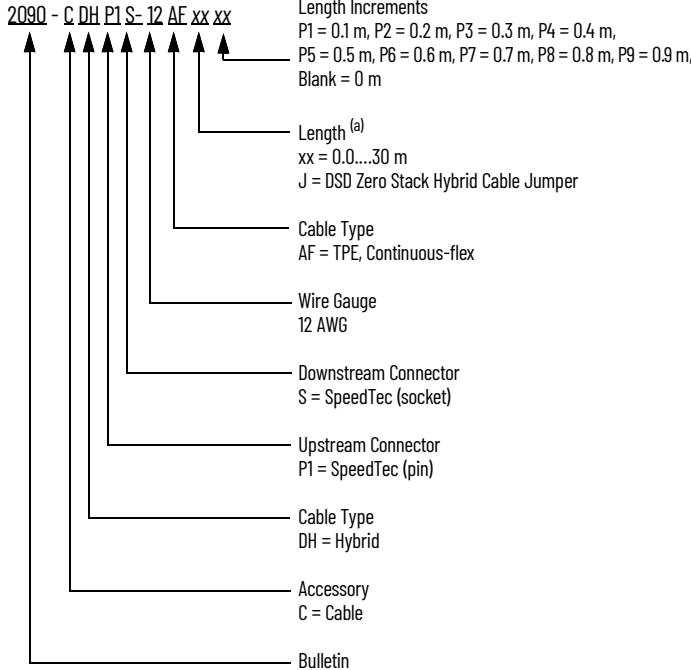
ArmorKinetix PIM to ArmorKinetix DSx Hybrid Cables

This cable connects the ArmorKinetix® Power Interface Module (PIM) to either the ArmorKinetix Distributed Servo Motor (DSM) or the Distributed Servo Drive (DSD).



Armorkinetix DSx to DSx Hybrid Cables

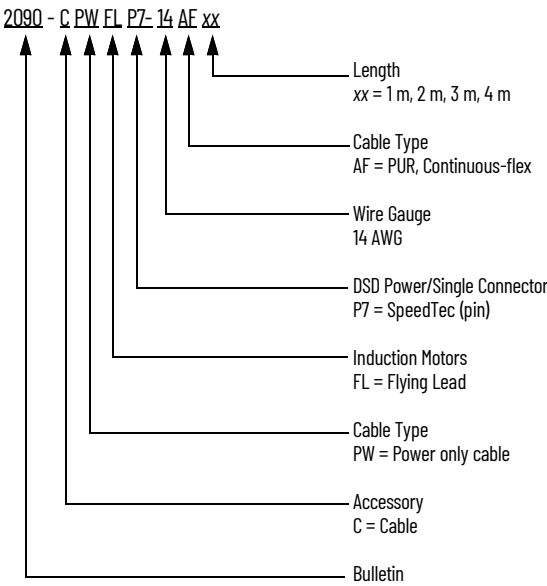
This cable connects distributed servo drives and motors to each other.



(a) For 0.5...5 m cable lengths, cables are available in 0.1 m increments. For cable lengths longer than 5 m, cables are available in 0.5 m increments.

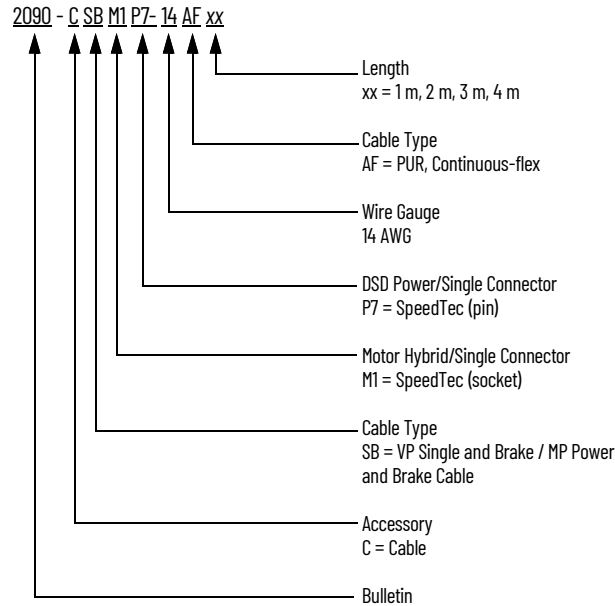
Armorkinetix DSD to Induction Motor Power Cable

This cable connects the DSD to induction motors with open loop, Hiperface, incremental TTL, and generic SIN/COS encoders.



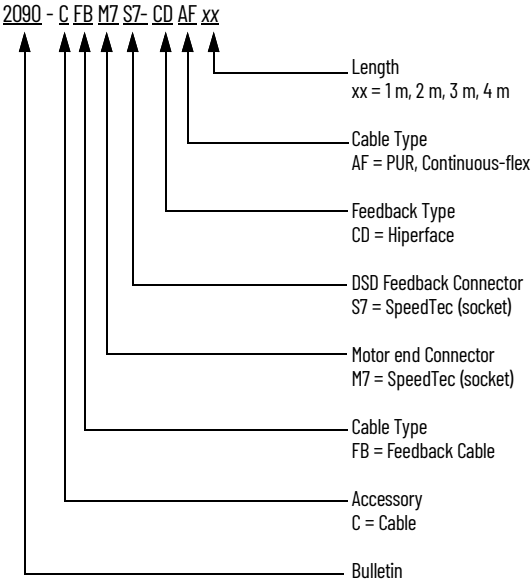
Armorkinetix DSD to Kinetix VPL/MPL Motor Power Cable

This cable connects the distributed servo drive to Kinetix® VPL/MPL motors.



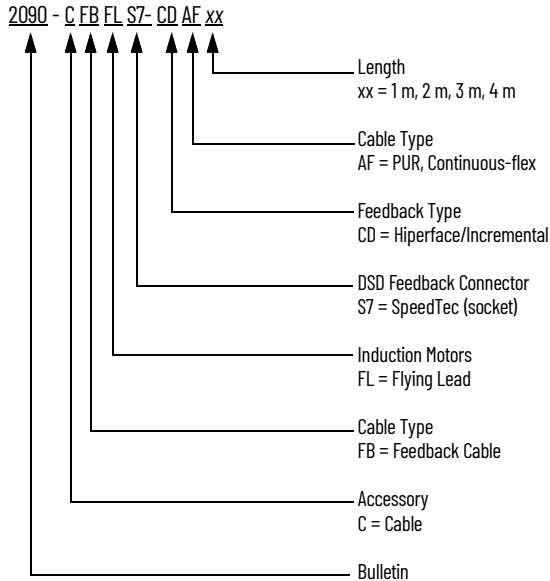
Armorkinetix DSD to Kinetix Motor Feedback Cable

This cable connects the Kinetix motor feedback to the distributed servo drive.



ArmorKinetix DSD to Induction Motor Feedback or Auxiliary Feedback Cable

This cable connects an induction motor feedback or auxiliary feedback device to the distributed servo drive.



Before You Begin

Remove all packing material from within and around the item. After unpacking, verify the catalog number against the purchase order, and visually inspect the cable and each connector for damage. If necessary, immediately notify the carrier of any shipping damage.

Cables are stored and shipped in a coil, and will retain this shape unless you straighten the cable. To straighten a cable, hang a short cable from its mid-point or lay a long cable on the floor in a straight line. Any coiling that persists should relax within 24 hours. Doing this results in a cable that is easier to install.

Observe the following precautions when installing the cables in a servo system. Failure to observe these safety notices could result in personal injury or damage to the motor and equipment.



SHOCK HAZARD: To avoid the hazard of electrical shock, be sure to ground any cable providing power at a minimum of one point. To prevent the build-up of electrical energy, factory-supplied cables use one of these grounding techniques:

- Bond the overall shield to the connector housing.
 - Make sure there is a direct connection-to-ground for each cable shield.
 - Connect an exposed cable braid or a ground wire, if present, to the power cable clamp, housing, or another suitable chassis ground.
- Failure to observe these safety procedures could result in personal injury or equipment damage.



ATTENTION: Arcing or unexpected motion can occur if cables are connected or disconnected while power is applied to the ArmorKinetix system. Before working on an ArmorKinetix system, disconnect power and wait the full time interval as indicated in the warning on the PIM module or verify the DC bus voltage at the PIM module measures less than 60V DC. Failure to observe this precaution could result in severe bodily injury or loss of life, and damage to the product will occur.



ATTENTION: The maximum length of cabling between the PIM and the last DSD or DSM unit in the system must not exceed 140 m (459 ft).



ATTENTION: The hybrid connectors on the DSD or DSM modules are designed to be rotated into a fixed position during installation, and remain in that position without further adjustment. Strictly limit the applied forces and the number of times the hybrid connectors are rotated to make sure the connectors meet the specified IP ratings.

Apply force only to the connector and cable plug. Do not apply force to the cable extending from the cable plug. No tools, for example pliers or vise-grips, should be used to assist with the rotation of the connector.

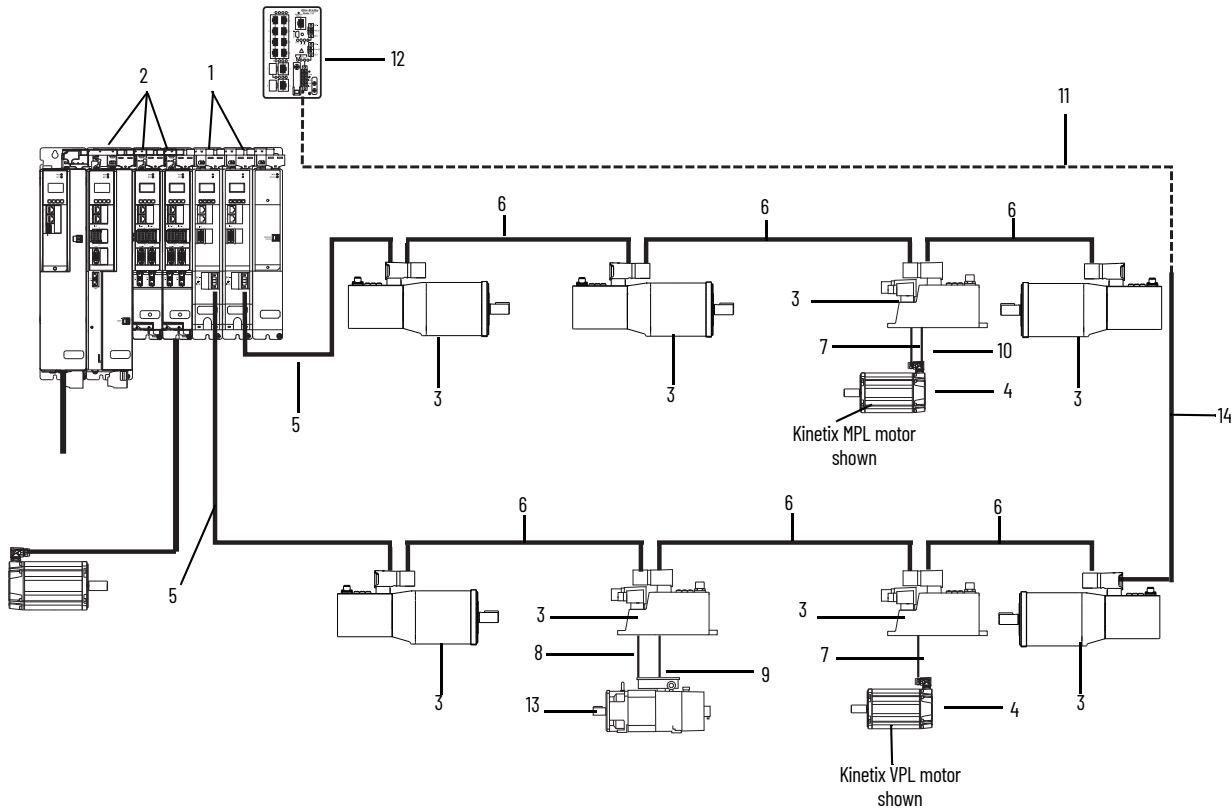
Failure to observe safety precautions could result in damage to the DSD or DSM module and its components.



ATTENTION: To avoid personal injury and damage to the DSD or DSM, do not lift or handle the DSD or DSM by the hybrid connectors.

ArmorKinetix Cable System Overview

Each ArmorKinetix PIM module supports up to 24 ArmorKinetix DSD and/or DSM modules. Total cable length for the ArmorKinetix system (PIM, DSD including motor connections, and DSM modules) is 140 m (459 ft) maximum.



Guidelines for Cable and Connector Installation

Follow these guidelines when installing cables and see the Installation topics for each cable type.

- [Armorkinetix PIM to DSx Hybrid Cable Installation on page 5](#)
- [Armorkinetix DSx to DSx Hybrid Cable Installation on page 6](#)
- [Armorkinetix DSD to Kinetix VPL/MPL Motor Power/Feedback Cable Installation on page 7](#)
- [Armorkinetix DSD to Induction Motor Power Cable Installation on page 7](#)
- [Armorkinetix DSD to Kinetix Motor Feedback Cable Installation on page 8](#)
- [Armorkinetix DSD to Induction Motor Feedback or Auxiliary \(stand-alone\) Feedback Cable Installation on page 8](#)
- [Armorkinetix 2090 Hybrid Connector Communication Extension on page 9](#)



ATTENTION: Arcing or unexpected motion can occur if cables are connected or disconnected while power is applied to the Armorkinetix system. Before working on an Armorkinetix system, disconnect power and wait the full time interval as indicated in the warning on the DSx module or verify the DC bus voltage at the PIM module measures less than 60V DC. Failure to observe this precaution could result in severe bodily injury or loss of life, and damage to the product will occur.

Observe these restrictions when installing the connecting cables:

- Connect Armorkinetix 2090 cables only after the modules are mounted.
- Prevent the cable from flexing within 150 ± 25 mm (6 ± 1 in.) installation areas.
- Bend cables to a specific shape only in the bend zone area. See [Cable Bend Radius Specifications on page 9](#) for more information.
- Provide cable supports at 3 m (10 ft) intervals along the cable run to reduce tension and flexing at the connectors and other features on the cable.
- Always form a drip loop in the cables directly before each cable enters and exits the module. A drip loop is a low spot in the cable that lets liquids gather and drip off the cable rather than flow along the cable to an electrical connection or the motor.



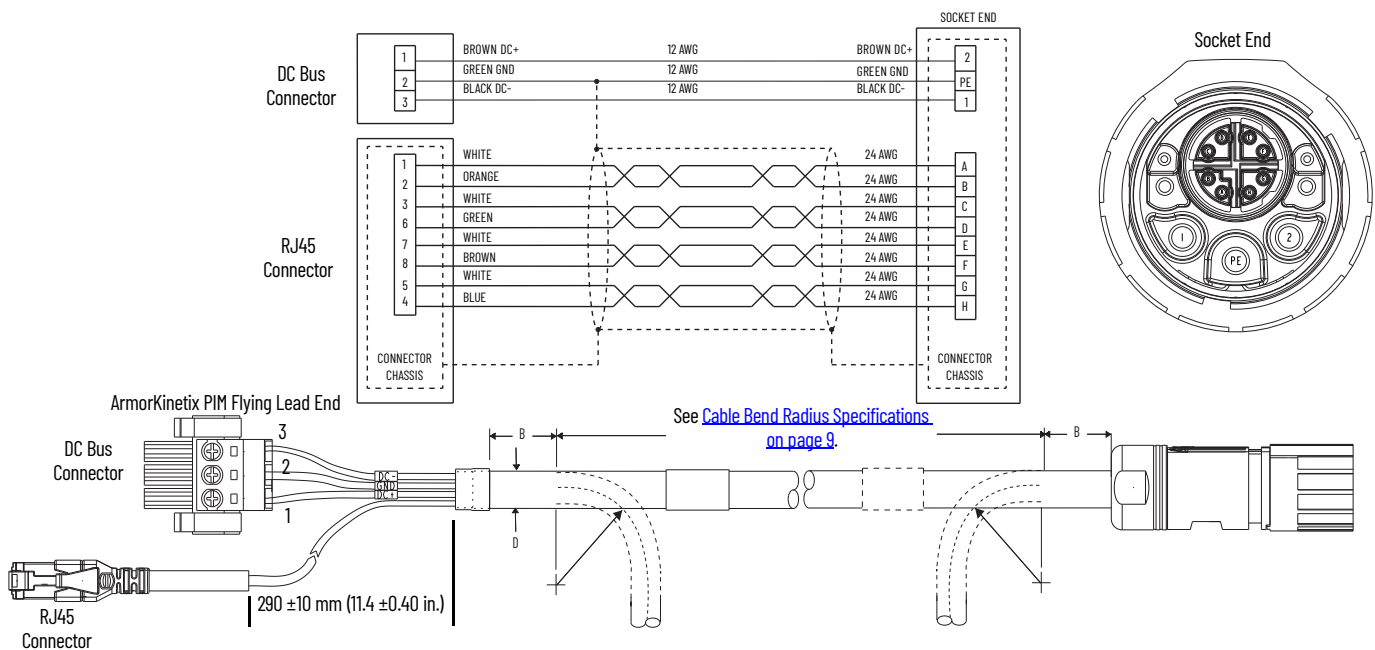
ATTENTION: Cable connectors must be properly aligned before the connection is secured with the recommended degrees of rotation or torque value. Improper connector alignment is indicated by the need for excessive force, such as the use of tools, to fully seat connectors. Failure to observe these safety procedures could result in damage to the device, cables, and connector components.

- Tighten connectors properly.
- Use terminators when no additional connections are made. See [page 6](#) for connector terminator information.

Armorkinetix PIM to DSx Hybrid Cable Installation

Use these guidelines as a reference when connecting the hybrid cable to the PIM module.

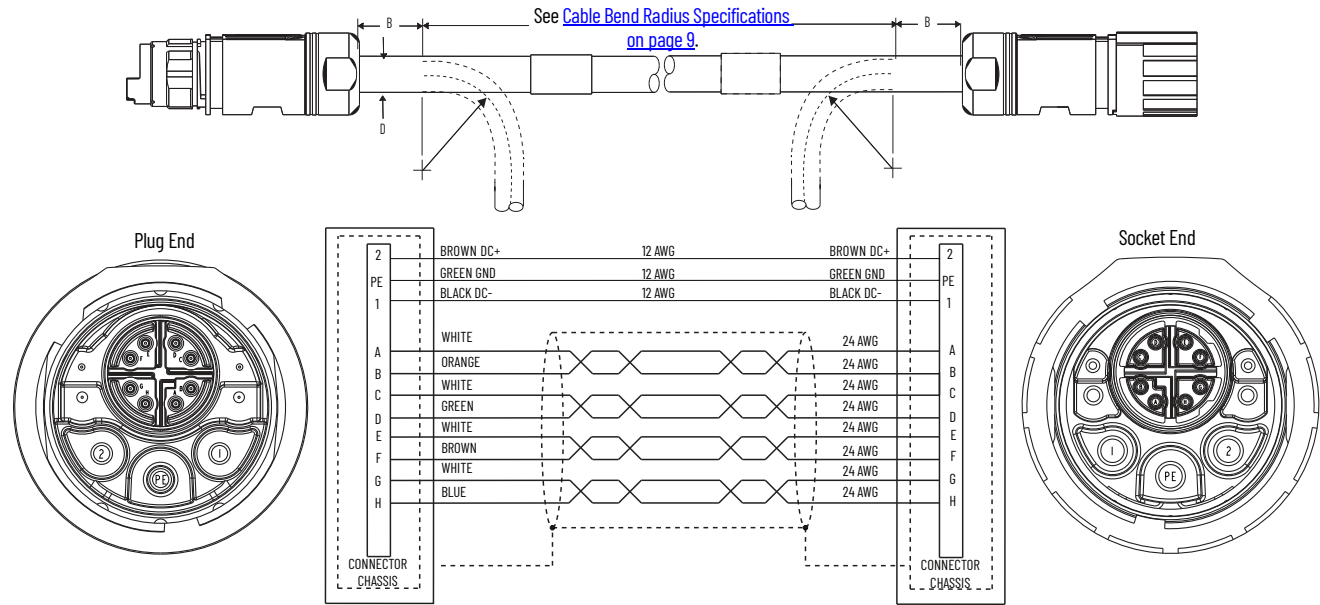
Armorkinetix PIM to DSx Hybrid Cable Pinout - 2090-CDHIFS-12AFxxxx



1. Route the cable to the module.
2. Insert the connector plug into the module connector.

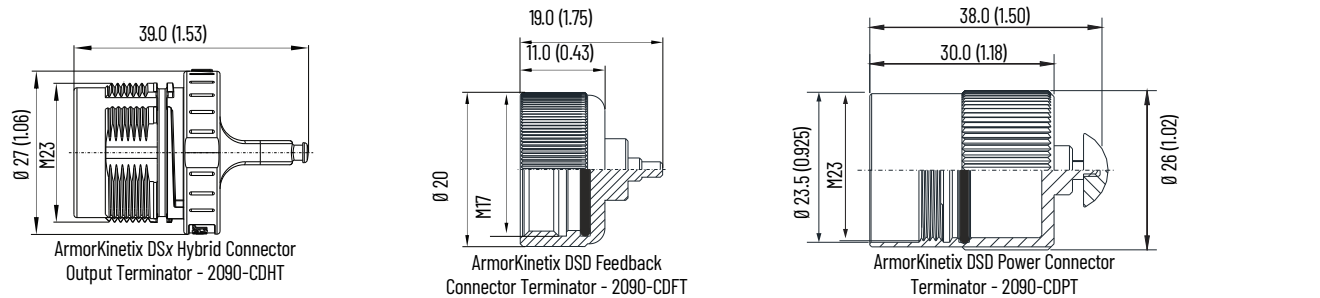
ArmorKinetix DSx to DSx Hybrid Cable Installation

ArmorKinetix DSx to DSx Hybrid Cable and ArmorKinetix DSx to DSx Zero Stack Jumper Cable Pinouts - 2090-CDHP1S-12AFxxxx and 2090-CDHP1S-12AFJ



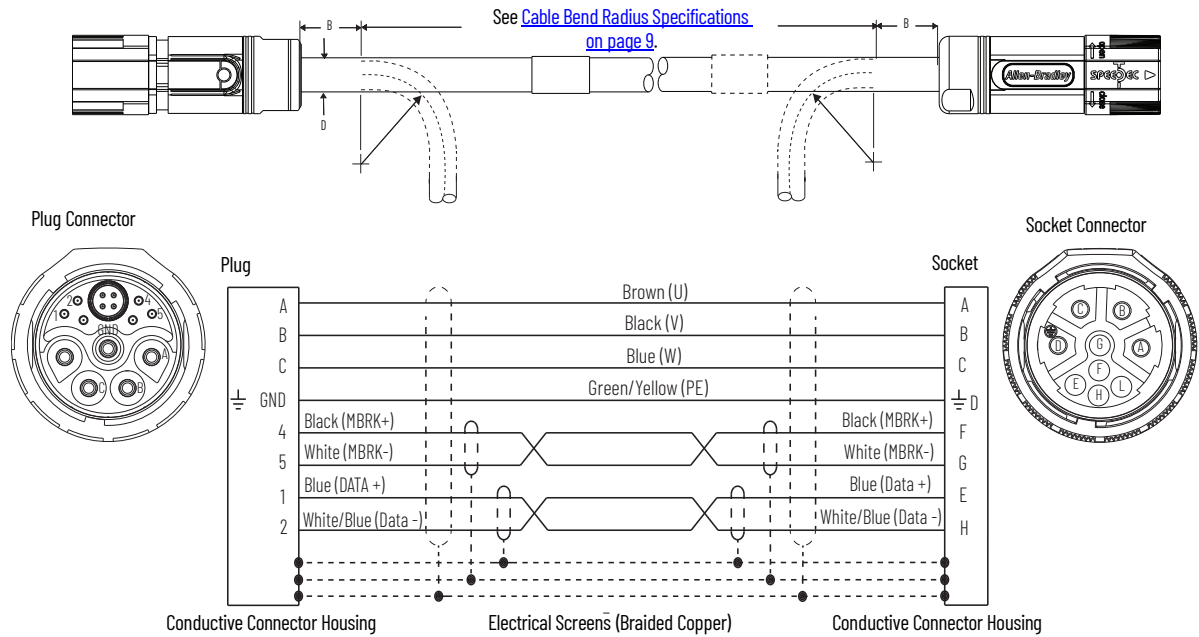
Connector Terminator Dimensions - 2090-CDHT, 2090-CDFT, 2090-CDPT

Dimensions in millimeters (inches). Dimensions are not intended to be used for manufacturing purposes.



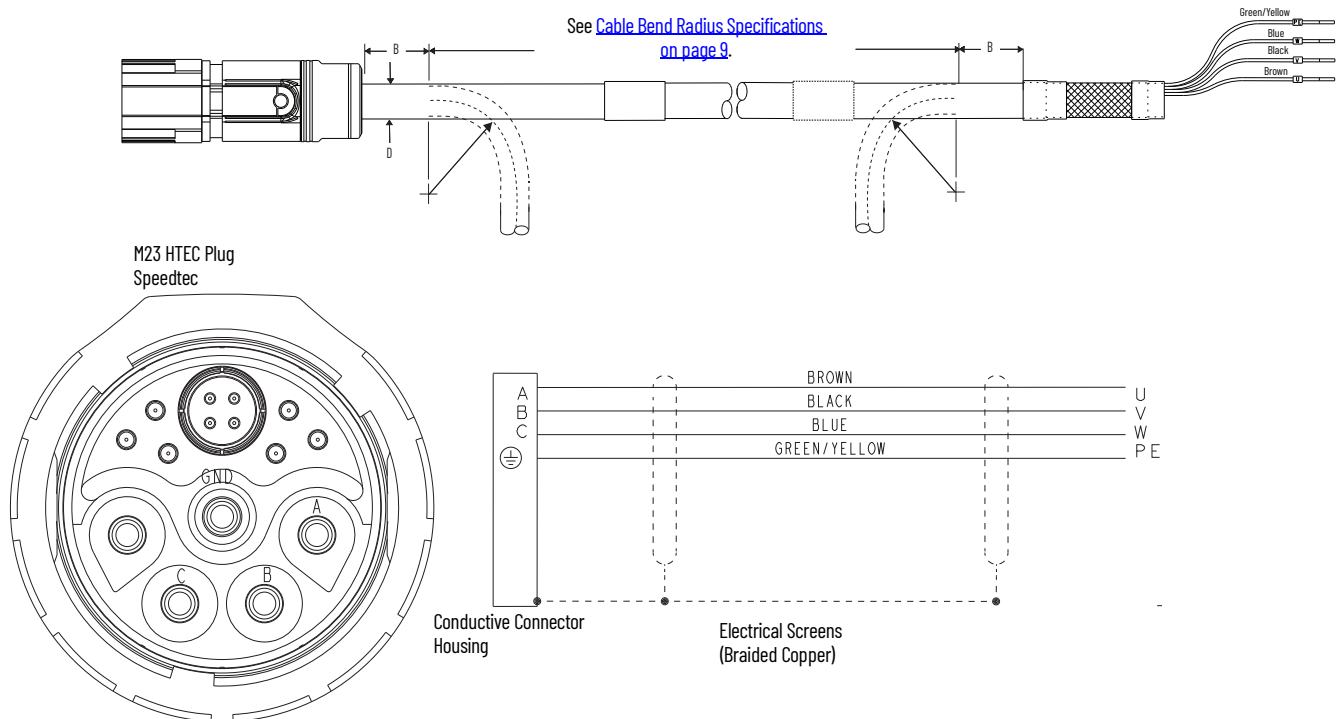
ArmorKinetix DSD to Kinetix VPL/MPL Motor Power/Feedback Cable Installation

ArmorKinetix DSD to Kinetix VPL/MPL Power/Feedback Cable (2090-CSBM1P7-14AFxx)



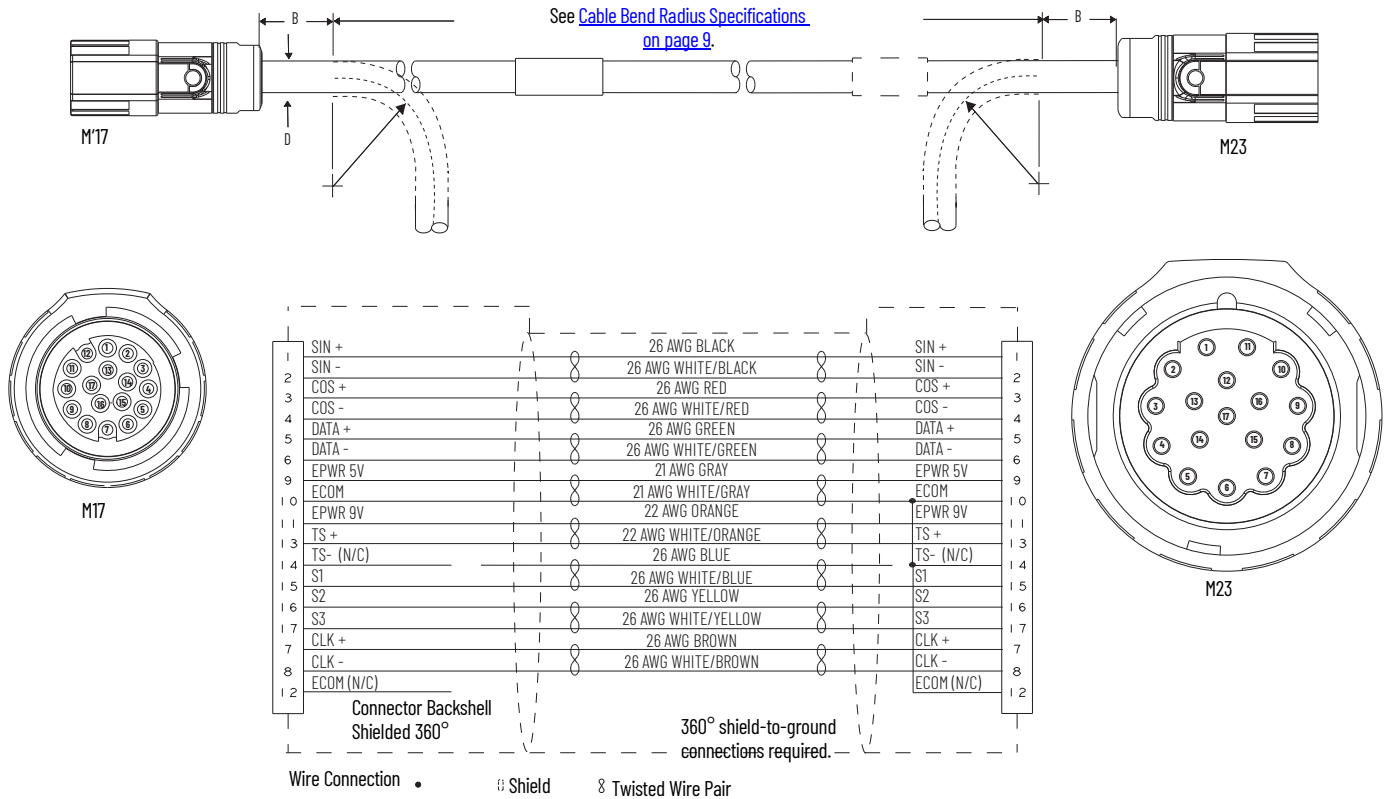
ArmorKinetix DSD to Induction Motor Power Cable Installation

ArmorKinetix DSD to Induction Motor Power Cable (2090-CPWFLP7-14AFxx)



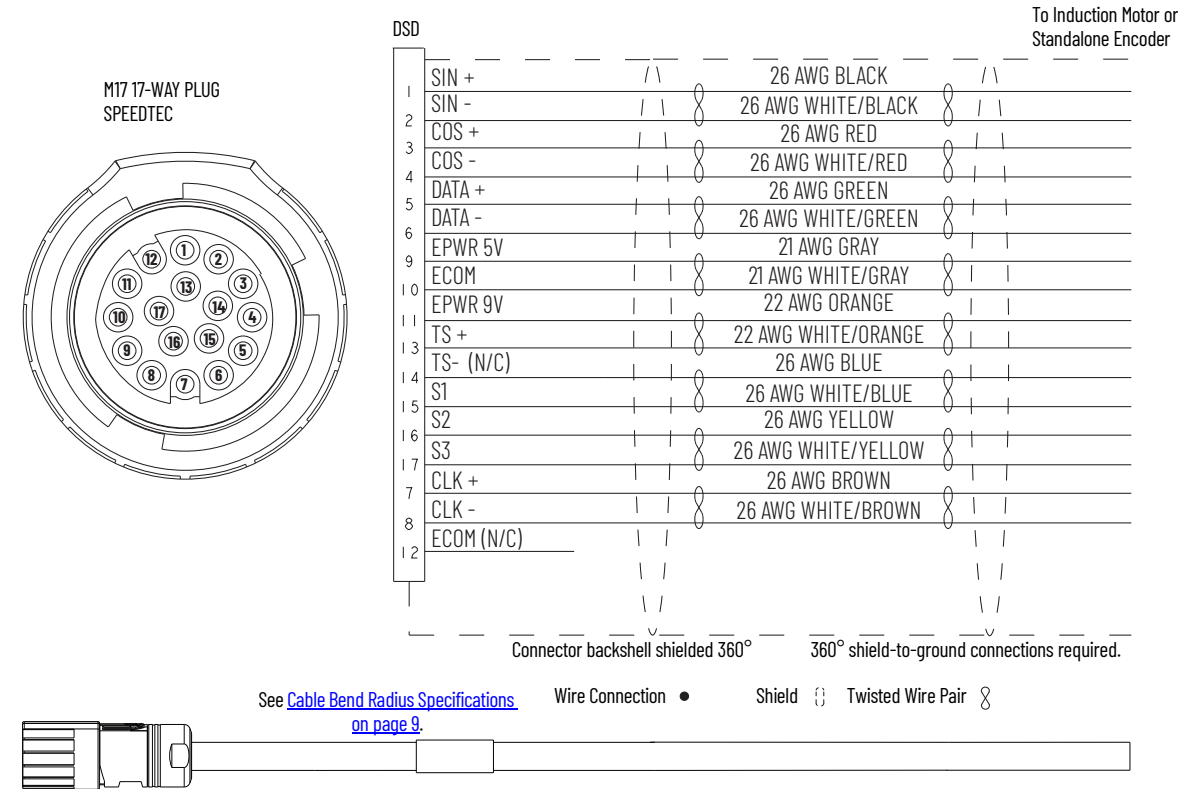
ArmorKinetix DSD to Kinetix Motor Feedback Cable Installation

ArmorKinetix DSD to Kinetix Motor Feedback Cable (2090-CFBM7S7-CDAFxx)



ArmorKinetix DSD to Induction Motor Feedback or Auxiliary (stand-alone) Feedback Cable Installation

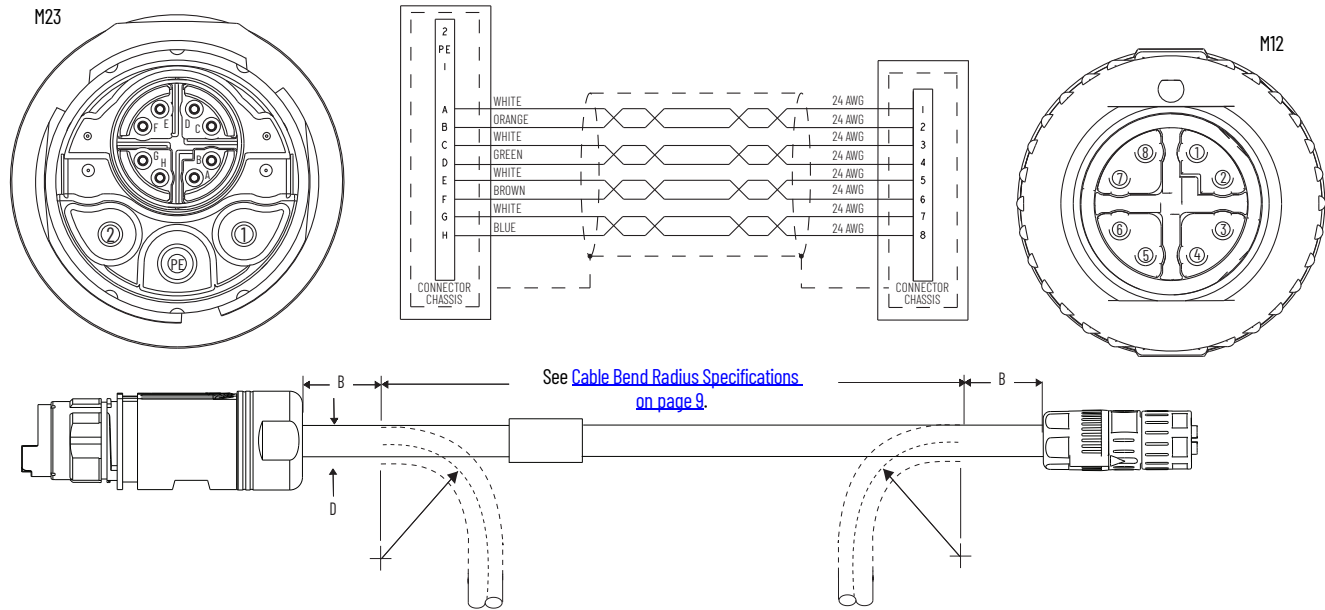
ArmorKinetix DSD to Induction Motor Feedback or Auxiliary Feedback Cable (stand-alone) (2090-CFBFLS7-CDAFxx)



ArmorKinetix 2090 Hybrid Connector Communication Extension

The hybrid connector communication extension has only the communication/Ethernet pins populated on the M23 side, and passes through to an M12 X-coded Ethernet connection on the other side.

ArmorKinetix DSx Hybrid Connector - Communication Extension Jumper-cable (2090-CDET)



Cable Bend Radius Specifications

Bend Radius Definitions

Type of Bend Radius	Type of Cable	Description
Static bend radius	Continuous-flex	The static (installation) bend radius and dimension B is: • 5 times the cable diameter. • Do not begin a static bend inside dimension B. • Use this measurement when routing the cable in a non-flex application between motor and drive (the bend area). • The bend area is where standard (non-flex) or continuous-flex cables can be bent to their specified bend radius.
Continuous bend radius	Continuous-flex	The continuous bend radius for Bulletin 2090 single motor cables is: • 10 times the cable diameter. • Secure the continuous-flexing area, the recommended cable diameters (dimension B) from each end of the cable, with a rigid mount that helps prevent the cable from flexing where it connects to the motor or shield clamp. Refer to the cable carrier manufacturer's recommendations for procedure and dimensions related to flexing applications. • Use this measurement when routing the cable in a continuous-flex application between motor and drive (the continuous-flexing area). • The continuous flexing area is where continuous-flex cables can be flexed repeatedly. • Install the cable along the neutral axis to make sure that the cable is not in contact with the inner radius of the cable carrier while flexing.

ArmorKinetix Cable Specification - Bend Radius

Cable Cat. No.	Wire Size	D	B	Static (installation) bend radius	Continuous Bend Radius	Continuous Bend Radius Factor	Expected Flex cycle at Rated Radius
2090-CDHFS-12AFxxxx	12	13.2	92.4	66	132	10	10 M
2090-CDHPS-12AFxxxx	12	13.2	92.4	66	132	10	10 M
2090-CSBM1P7-14AFxx	14	15.2	76	76	106.4	7	10 M
2090-CPWFLP7-14AFxx	14	15.2	76	76	106.4	7	10 M
2090-CFBM7S7-CDAFxx	—	9.8	68.6	49	98	10	10 M
2090-CFBFLS7-CDAFxx	—	9.8	68.6	49	98	10	10 M
2090-CDET	24	7	49	35	70	10	10 M

ArmorKinetix Cables Environmental Specifications

Description	Value
Storage Temperature	-40...+85 °C (-40...+185 °F)
Humidity	5...95% noncondensing
IP Protection	IP66, IP67
Mechanical Shock and Vibration	25 g shock and 5 g vibrate
Oil Resistance	Oil resistance to UL 50E Type 12
UV Resistance	Sunlight resistance per UL 50E Type 12
Water Absorption	Water absorption to be tested per UL 1581 - IEC 60811 for 168 hours (7 days).

Additional Resources

These documents contain additional information concerning related products from Rockwell Automation. You can view or download publications at rok.auto/literature.

Resource	Description
ArmorKinetix System User Manual, publication 2198-UM006	Provides information on installing, configuring, startup, troubleshooting, and applications for your ArmorKinetix drive system.
Kinetix® 5700 Servo Drives User Manual, publication 2198-UM002	Provides information to install, configure, start, and troubleshoot your Kinetix 5700 servo drive system.
Kinetix Rotary and Linear Motion Cable Specifications Technical Data, publication KNX-TD004	Product specifications for Kinetix 2090 motor and interface cables.
Kinetix 5700 Drive Systems Design Guide, publication KNX-RM010	System design guide to select the required (drive specific) drive module, power accessory, feedback connector kit, and motor cable catalog numbers for your Kinetix 5700 drive system.
EtherNet/IP™ Network Devices User Manual, ENET-UM006	Describes how to configure and use EtherNet/IP devices to communicate on the EtherNet/IP network.
Ethernet Reference Manual, ENET-RM002	Describes basic Ethernet concepts, infrastructure components, and infrastructure features.
American Standards, Configurations, and Ratings: Introduction to Motor Circuit Design, publication IC-AT001	Provides an overview of American motor circuit design based on methods that are outlined in the NEC.
Safety Guidelines for the Application, Installation, and Maintenance of Solid-state Control, publication SG1-11	Designed to harmonize with NEMA Standards Publication No. ICS 1.1-1987 and provides general guidelines for the application, installation, and maintenance of solid-state control in the form of individual devices or packaged assemblies incorporating solid-state components.
Industrial Automation Wiring and Grounding Guidelines, publication 1770-4.1	Provides general guidelines for installing a Rockwell Automation industrial system.
Product Certifications website, rok.auto/certifications	Provides declarations of conformity, certificates, and other certification details.

Waste Electrical and Electronic Equipment (WEEE)



At the end of life, this equipment should be collected separately from any unsorted municipal waste.

Rockwell Automation maintains current product environmental compliance information on its website at rok.auto/pec.

Your comments help us serve your documentation needs better. If you have any suggestions on how to improve our content, complete the form at rok.auto/docfeedback.

For technical support, visit rok.auto/support.

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